



International Workshop on “Vehicle Technologies for Connected, Cooperative & Automated Mobility”

Wednesday 16 June 2021

13:30 – 17:30

PROGRAMME

13.30 : Opening Session

Presentation by the **European Commission**: Ludger Rogge, Tom Alkim, DG-RTD

Introduction to **ARCADE Project**: Stephane Dreher, ARCADE Coordinator, ERTICO

Overview of the **CCAM Partnership** (Cooperative, Connected and Automated Mobility): Armin Gräter, Chairman of the CCAM Partnership, BMW Group

Introduction to **Mobility.E Lighthouse & COSMOS Project**: Benjamin Wilsch, COSMOS Coordinator, VDI/VDE-IT

14.00 : Keynote Presentation on L3Pilot Project

Aria Etemad, L3Pilot Coordinator, Volkswagen Group Research



14.30 : Technical Session A

Focus on Environment Perception, Data fusion, Decision-Making and Artificial Intelligence

Moderated by Gereon Meyer, VDI/VDE-IT, & Margriet van Schijndel, TU Eindhoven

Michele Giorelli, Technical Manager of Advanced System Engineering, Aptiv

Eckard Steiger, Director of Industrial Cooperations Automated Driving, Bosch

Philip Hubertus, Product Manager Autonomous Driving, HERE

Cyprian Grassmann, Distinguished Engineer Radar System Engineering, INFINEON

Pierre-Olivier Millette, Director of Automated Driving Technical Policy EMEA, INTEL

Moritz Antlanger, System Architect, TTTech Auto

Samia Ahiad, System & Validation Metier Manager, Valeo

16.00 : **Keynote: SAE International's Standards Roadmap for Connected & Automated Road Vehicles**

Ed Straub, Director of the Office of Automation, SAE International

16.20 : Technical Session B

Focus on Safety, HMI (Human Machine Interaction), Human factors, Life-on-Board and Inclusiveness

Moderated by David Storer, CLEPA, & Peter Urban, IKA - RWTH Aachen

Alexander Gulde, Senior Director of Engineering, Autoliv

Zachary Bolton, Innovation Manager North America, Continental

Tim Leinmüller, Head of Fundamental Technology R&D Dept, Denso

Anna Rossi, Director Technology Partnerships, Faurecia

Alexander Kroeller, Manager Research & Innovation, TomTom